



## **SELF-TUNING CONTROL OF AN ELECTRO-HYDRAULIC ACTUATOR SYSTEM**

<sup>1</sup>R. Ghazali, <sup>1</sup>Y. M. Sam, <sup>1</sup>M. F. Rahmat, <sup>3</sup>K. Jusoff, <sup>1</sup>Zulfatman, <sup>2</sup>A. W. I. M. Hashim

<sup>1</sup>Department of Control and Instrumentation, Faculty of Electrical Engineering,  
Universiti Teknologi Malaysia, 81310 Skudai, Malaysia

<sup>2</sup>College of Science and Technology, International Campus,  
Universiti Teknologi Malaysia, 51400 Kuala Lumpur, Malaysia

<sup>3</sup>Department of Forest Production, Faculty of Forestry,  
Universiti Putra Malaysia, 43400 Serdang, Selangor, Malaysia

Emails: [yahaya@fke.utm.my](mailto:yahaya@fke.utm.my), [fuaad@fke.utm.my](mailto:fuaad@fke.utm.my), [rozaimi@ieee.org](mailto:rozaimi@ieee.org), [kjusoff@yahoo.com](mailto:kjusoff@yahoo.com)

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*Abstract- Due to time-varying effects in electro-hydraulic actuator (EHA) system parameters, a self-tuning control algorithm using pole placement and recursive identification is presented. A discrete-time model is developed using system identification method to represent the EHA system and residual analysis is used for model validation. A recursive least square (RLS) method with covariance resetting technique is proposed to estimate parameters of the discrete-time model. The results show the proposed control algorithm can adapt the changes occur in model parameters compared with the fixed controller. In conclusion, a self-tuning control is required in improving the EHS system performance in industrial positioning applications.*

**Index terms:** System identification, pole placement, recursive least square, electro hydraulic actuator system, self tuning control